

# Bisimulation and path logic for sheaves

Giovanni Ciná <sup>1</sup>   Sebastian Enqvist <sup>2</sup>

<sup>1</sup>ILLC

<sup>2</sup>ILLC and Lund University

TACL

25/06/2015

# Outline

- 1 Path logic and path bisimulation in concurrency
- 2 Example:  $\mathbf{Bran}_L$
- 3 Path logic on sheaves
- 4 Path bisimulation on sheaves

# Outline

- 1 Path logic and path bisimulation in concurrency
- 2 Example:  $\mathbf{Bran}_L$
- 3 Path logic on sheaves
- 4 Path bisimulation on sheaves

# A categorical notion of bisimulation

In the seminal paper [2] “Bisimulation from open maps” Joyal, Winskel and Nielsen:

- represented different models of concurrency in terms of presheaves over suitable ‘path categories’;

# A categorical notion of bisimulation

In the seminal paper [2] “Bisimulation from open maps” Joyal, Winskel and Nielsen:

- represented different models of concurrency in terms of presheaves over suitable ‘path categories’;
- offered a general notion of bisimulation as a **span of open maps**, namely arrows with a special path-lifting property;

# A categorical notion of bisimulation

In the seminal paper [2] “Bisimulation from open maps” Joyal, Winskel and Nielsen:

- represented different models of concurrency in terms of presheaves over suitable ‘path categories’;
- offered a general notion of bisimulation as a **span of open maps**, namely arrows with a special path-lifting property;
- showed that spans of open maps between presheaf models encompass the different notions of behavioural equivalence.

# A categorical notion of bisimulation

In the seminal paper [2] “Bisimulation from open maps” Joyal, Winskel and Nielsen:

- represented different models of concurrency in terms of presheaves over suitable ‘path categories’;
- offered a general notion of bisimulation as a **span of open maps**, namely arrows with a special path-lifting property;
- showed that spans of open maps between presheaf models encompass the different notions of behavioural equivalence.

In general path categories are just assumed to have an initial object  $I$ , while presheaf models  $F$  are only assumed to be rooted, i.e  $F(I) = \{*\}$ .

# From presheaves to labelled transition systems.

It was observed in a follow-up paper [3] that presheaves  $F : \mathbf{P}^{op} \rightarrow \mathbf{Set}$  can in turn be made into relational structures:

- $W = \{(P, x) \mid P \in \mathbf{P}_0, x \in F(P)\}$ ;
- for every morphism  $m$  in  $\mathbf{P}_1$  define  $(P, x)R_m(P', x')$  iff  $m : P \rightarrow P'$  in  $\mathbf{P}$  and  $F(m)(x') = x$ .



# From presheaves to labelled transition systems.

It was observed in a follow-up paper [3] that presheaves  $F : \mathbf{P}^{op} \rightarrow \mathbf{Set}$  can in turn be made into relational structures:

- $W = \{(P, x) \mid P \in \mathbf{P}_0, x \in F(P)\}$ ;
- for every morphism  $m$  in  $\mathbf{P}_1$  define  $(P, x)R_m(P', x')$  iff  $m : P \rightarrow P'$  in  $\mathbf{P}$  and  $F(m)(x') = x$ .

We can devise a notion of bisimulation on these relational structures that matches the bisimulation in terms of open maps. Such bisimulation is called **path bisimulation**.

# Path logic $\mathbb{P}L_{\mathbf{P}}$

On presheaf models over  $\mathbf{P}$ , the logic that is characteristic for path-bisimulation is called **path logic** ([2]):

$$\varphi ::= \perp \mid \neg\varphi \mid \bigwedge_{j \in J} \varphi_j \mid \langle m \rangle \varphi \mid \overline{\langle m \rangle} \varphi$$

where  $m \in \mathbf{P}_1$  and  $J$  has cardinality  $\max\{|\mathbf{P}(X, Y)| \mid X, Y \in \mathbf{P}_0\}$ .

# Path logic $\mathbb{P}L_{\mathbf{P}}$

On presheaf models over  $\mathbf{P}$ , the logic that is characteristic for path-bisimulation is called **path logic** ([2]):

$$\varphi ::= \perp \mid \neg\varphi \mid \bigwedge_{j \in J} \varphi_j \mid \langle m \rangle \varphi \mid \overline{\langle m \rangle} \varphi$$

where  $m \in \mathbf{P}_1$  and  $J$  has cardinality  $\max\{|\mathbf{P}(X, Y)| \mid X, Y \in \mathbf{P}_0\}$ .

This logic is interpreted on the relational counterparts of presheaf models. Given an object  $P$  of  $\mathbf{P}$ , a presheaf model  $F$  and  $p \in F(P)$ :

$$(P, p) \models \langle m \rangle \varphi \quad \text{iff} \quad \text{there exist } P', p', (P, x)R_m(P', x') \\ \text{and } (P', p') \models \varphi.$$

# Path logic $\mathbb{P}L_{\mathbf{P}}$

On presheaf models over  $\mathbf{P}$ , the logic that is characteristic for path-bisimulation is called **path logic** ([2]):

$$\varphi ::= \perp \mid \neg\varphi \mid \bigwedge_{j \in J} \varphi_j \mid \langle m \rangle \varphi \mid \overline{\langle m \rangle} \varphi$$

where  $m \in \mathbf{P}_1$  and  $J$  has cardinality  $\max\{|\mathbf{P}(X, Y)| \mid X, Y \in \mathbf{P}_0\}$ .

This logic is interpreted on the relational counterparts of presheaf models. Given an object  $P$  of  $\mathbf{P}$ , a presheaf model  $F$  and  $p \in F(P)$ :

$$(P, p) \models \langle m \rangle \varphi \quad \text{iff} \quad \text{there exist } P', p', (P, x)R_m(P', x') \\ \text{and } (P', p') \models \varphi.$$

The condition for  $\overline{\langle m \rangle} \varphi$  is that of a backward-looking modality.

# Outline

- 1 Path logic and path bisimulation in concurrency
- 2 Example:  $\mathbf{Bran}_L$
- 3 Path logic on sheaves
- 4 Path bisimulation on sheaves

## Definition

Call  $\mathbf{T}_L$  the category of pointed transition systems with labels  $L$ , where morphisms preserve transitions and initial states. Call  $\mathbf{Tree}_L$  the subcategory of  $\mathbf{T}_L$  consisting of trees. Call  $\mathbf{Bran}_L$  (a skeleton of) the subcategory consisting of only branches, i.e. linear paths.

## Definition

Call  $\mathbf{T}_L$  the category of pointed transition systems with labels  $L$ , where morphisms preserve transitions and initial states. Call  $\mathbf{Tree}_L$  the subcategory of  $\mathbf{T}_L$  consisting of trees. Call  $\mathbf{Bran}_L$  (a skeleton of) the subcategory consisting of only branches, i.e. linear paths.

We can encode pointed transition systems with labels  $L$  into the presheaf category  $\mathbf{Set}^{\mathbf{Bran}_L^{op}}$  ([2], [3]):

$$\begin{array}{ccc}
 \mathbf{T}_L & \xrightarrow{Pre} & \mathit{rooted}(\mathbf{Set}^{\mathbf{Bran}_L^{op}}) \\
 & \searrow u & \downarrow \simeq \\
 & & \mathbf{Tree}_L
 \end{array}$$

## Theorem ([2])

*For transition systems we have that:*

- *Open maps are  $p$ -morphisms*
- *given two transition systems  $M_1$  and  $M_2$ , TFAE:*
  - 1  *$M_1$  and  $M_2$  are bisimilar*
  - 2 *there is a span of open maps between (the presheaf models of)  $M_1$  and  $M_2$*
  - 3 *there is a path-bisimulation between (the relational counterpart of the presheaf models of)  $M_1$  and  $M_2$*



# Outline

- 1 Path logic and path bisimulation in concurrency
- 2 Example:  $\mathbf{Bran}_L$
- 3 Path logic on sheaves
- 4 Path bisimulation on sheaves

## ...and sheaves?

There is a long tradition of interaction between Modal Logic and Topology, while on the other hand we know that sheaves are presheaves with a special topological significance.

## ...and sheaves?

There is a long tradition of interaction between Modal Logic and Topology, while on the other hand we know that sheaves are presheaves with a special topological significance. Question:

can we **express interesting properties of sheaves** over topological spaces **with path logic**?

## ...and sheaves?

There is a long tradition of interaction between Modal Logic and Topology, while on the other hand we know that sheaves are presheaves with a special topological significance. Question:

can we **express interesting properties of sheaves** over topological spaces **with path logic**?

Given a topological space  $\mathbb{X}$ , we consider the sheaves from the poset category  $\text{Open}(\mathbb{X})$ , hence the modalities of path logic are labelled by the inclusions between opens.

# A case study: Contextuality

A sheaf-theoretic treatment of non-locality and contextuality was initiated in [1] by Abramsky and Brandenburger.

## A case study: Contextuality

A sheaf-theoretic treatment of non-locality and contextuality was initiated in [1] by Abramsky and Brandenburger. Given a set of measurements  $X$  and a set of outcome  $O$ , they describe empirical system as special presheaves  $S : \wp(X)^{op} \rightarrow \text{Set}$  defined on objects as

$$U \subseteq X \quad \mapsto \quad S(U) \subseteq O^U$$

and on arrows as function restrictions.

# A case study: Contextuality

A sheaf-theoretic treatment of non-locality and contextuality was initiated in [1] by Abramsky and Brandenburger. Given a set of measurements  $X$  and a set of outcome  $O$ , they describe empirical system as special presheaves  $S : \wp(X)^{op} \rightarrow Set$  defined on objects as

$$U \subseteq X \quad \mapsto \quad S(U) \subseteq O^U$$

and on arrows as function restrictions.

Elements of  $O^U$  are called **sections**; they are a joint assignment of outcomes to the measurements in  $U$ . Elements of  $O^X$  are called **global sections**.

# A case study: Contextuality

The authors single out two key properties of empirical systems:

- 1 An empirical system  $S$  is called **strongly contextual** if there are no global sections:  $S(X) = \emptyset$ .
- 2 An empirical system  $S$  is called **weakly contextual** if there is a section  $s$  over a subset  $U$  that cannot be extended to a global section.



# A case study: Contextuality

The authors single out two key properties of empirical systems:

- 1 An empirical system  $S$  is called **strongly contextual** if there are no global sections:  $S(X) = \emptyset$ .
- 2 An empirical system  $S$  is called **weakly contextual** if there is a section  $s$  over a subset  $U$  that cannot be extended to a global section.

It turns out that both properties can be captured in the path logic over the poset  $\wp(X)$  (a discrete topology):

- 1  $\neg\langle\emptyset, X\rangle\top$
- 2  $\bigvee_{U\subseteq X}\langle\emptyset, U\rangle\neg\langle U, X\rangle\top$

# Beyond Contextuality

It turns out these and other properties expressible in path logic are of general significance for sheaves over topological spaces.

## Beyond Contextuality

It turns out these and other properties expressible in path logic are of general significance for sheaves over topological spaces. Other examples:

- the sheaf of sections of a covering map  $\pi : \mathbb{X} \rightarrow \mathbb{X}'$ : the satisfaction of the contextuality formulas tells us to what extent the covering space  $\mathbb{X}$  'looks like'  $\mathbb{X}'$  globally.
- flabby sheaves over  $\text{Open}(\mathbb{X})$ : sheaves whose restriction maps are surjective, can be defined in path logic by  $\bigwedge_{U \in \text{Open}(\mathbb{X})} [\emptyset, U] \langle U, X \rangle \top$

# Outline

- 1 Path logic and path bisimulation in concurrency
- 2 Example:  $\mathbf{Bran}_L$
- 3 Path logic on sheaves
- 4 Path bisimulation on sheaves

# Path bisimulation on sheaves

We saw that path logic precisely captures path bisimulations and that given a pair of path bisimilar sheaves, we can construct a span of open maps connecting them. However, the presheaf at the “vertex” may not be a sheaf.

# Path bisimulation on sheaves

We saw that path logic precisely captures path bisimulations and that given a pair of path bisimilar sheaves, we can construct a span of open maps connecting them. However, the presheaf at the “vertex” may not be a sheaf. Fix:

## Definition (Locality axiom for path bisimulations)

Suppose given a covering  $(U_i)_{i \in I}$  of an open  $U$ , sheaves  $Q_1, Q_2 : \text{Open}(\mathbb{X})^{op} \rightarrow \mathbf{Set}$  and a path bisimulation  $Z$ . We say  $Z$  satisfies **Locality** if for all  $p \in Q_1(U)$  and  $q \in Q_2(U)$  such that  $(p|_{U_i}^{Q_1}, q|_{U_i}^{Q_2}) \in Z_{U_i}$  for all  $i \in I$ , we have  $(p, q) \in Z_U$ .

# Path bisimulation on sheaves

We saw that path logic precisely captures path bisimulations and that given a pair of path bisimilar sheaves, we can construct a span of open maps connecting them. However, the presheaf at the “vertex” may not be a sheaf. Fix:

## Definition (Locality axiom for path bisimulations)

Suppose given a covering  $(U_i)_{i \in I}$  of an open  $U$ , sheaves  $Q_1, Q_2 : \text{Open}(\mathbb{X})^{\text{op}} \rightarrow \mathbf{Set}$  and a path bisimulation  $Z$ . We say  $Z$  satisfies **Locality** if for all  $p \in Q_1(U)$  and  $q \in Q_2(U)$  such that  $(p|_{U_i}, q|_{U_i}) \in Z_{U_i}$  for all  $i \in I$ , we have  $(p, q) \in Z_U$ .

## Proposition

*If two sheaves are related by a path bisimulation satisfying the Locality axiom then they are also related by a span of open maps.*

# Path bisimulation on sheaves

The conditions for a proper characterization of the span are not yet known. We can however characterize co-spans.



# Path bisimulation on sheaves

The conditions for a proper characterization of the span are not yet known. We can however characterize co-spans.

## Definition (Gluing axiom for path bisimulations)

Suppose given  $(U_i)_{i \in I}$  covering of  $U$ , sheaves  $Q_1, Q_2 : \text{Open}(\mathbb{X})^{op} \rightarrow \mathbf{Set}$  and a path bisimulation  $Z$ . We say  $Z$  satisfies **Glueing** if there are two families  $(p_i)_{i \in I}$  and  $(q_i)_{i \in I}$  with  $p_i \in Q_1(U_i)$  and  $q_i \in Q_2(U_i)$  for all  $i$  and moreover for all  $i, j$   $(p_i|_{U_i \cap U_j}^{Q_1}, q_j|_{U_i \cap U_j}^{Q_2}) \in Z$  then there exist two elements  $p \in Q_1(U)$  and  $q \in Q_2(U)$  such that  $(p, q) \in Z$  and, for all  $i$ ,  $(p|_{U_i}^{Q_1}, q_i) \in Z$  and  $(q|_{U_i}^{Q_2}, p_i) \in Z$ .

# Path bisimulation on sheaves

The conditions for a proper characterization of the span are not yet known. We can however characterize co-spans.

## Definition (Gluing axiom for path bisimulations)

Suppose given  $(U_i)_{i \in I}$  covering of  $U$ , sheaves  $Q_1, Q_2 : \text{Open}(\mathbb{X})^{op} \rightarrow \mathbf{Set}$  and a path bisimulation  $Z$ . We say  $Z$  satisfies **Glueing** if there are two families  $(p_i)_{i \in I}$  and  $(q_i)_{i \in I}$  with  $p_i \in Q_1(U_i)$  and  $q_i \in Q_2(U_i)$  for all  $i$  and moreover for all  $i, j$   $(p_i|_{U_i \cap U_j}^{Q_1}, q_j|_{U_i \cap U_j}^{Q_2}) \in Z$  then there exist two elements  $p \in Q_1(U)$  and  $q \in Q_2(U)$  such that  $(p, q) \in Z$  and, for all  $i$ ,  $(p|_{U_i}^{Q_1}, q_i) \in Z$  and  $(q|_{U_i}^{Q_2}, p_i) \in Z$ .

## Definition

A path bisimulation  $Z$  is said to be **di-functional** if  $(p, q) \in Z$ ,  $(p', q) \in Z$  and  $(p', q') \in Z$  entail  $(p, q') \in Z$ .

# Path bisimulation on sheaves

## Theorem

*Two sheaves  $Q_1$  and  $Q_2$  are related by a co-span of open maps*

$$Q_1 \rightarrow P \leftarrow Q_2$$

*where  $P$  is a sheaf, if and only if they are related by a di-functional path bisimulation that satisfies the Gluing and Locality axioms.*

# Path bisimulation on sheaves

## Theorem

*Two sheaves  $Q_1$  and  $Q_2$  are related by a co-span of open maps*

$$Q_1 \rightarrow P \leftarrow Q_2$$

*where  $P$  is a sheaf, if and only if they are related by a di-functional path bisimulation that satisfies the Gluing and Locality axioms.*

## Proposition

*Spans and co-spans of open maps are equivalent in the category of sheaves over a topological space if and only if the unit  $\eta_P : P \rightarrow L(P)$  is open, where  $L$  is the sheafification functor.*

# Capturing sheaves in hybrid path logic

The property of being a sheaf is not expressible in path logic, since there are sheaves that are path bisimilar to proper presheaves.

## Capturing sheaves in hybrid path logic

The property of being a sheaf is not expressible in path logic, since there are sheaves that are path bisimilar to proper presheaves.

We need to add some expressive power. The most natural extension of the language is a **hybrid path logic**. In this language we can encode the locality and glueing axioms for sheaves into formulas  $Loc$  and  $Glu$ .

# Capturing sheaves in hybrid path logic

The property of being a sheaf is not expressible in path logic, since there are sheaves that are path bisimilar to proper presheaves.

We need to add some expressive power. The most natural extension of the language is a **hybrid path logic**. In this language we can encode the locality and glueing axioms for sheaves into formulas  $Loc$  and  $Glu$ .

## Proposition

*A rooted presheaf  $P$  is a sheaf iff  $P$  satisfies  $Loc \wedge Glu$*

## Conclusions and further work

We have:

- 1 shown that interesting properties of sheaves can be expressed in path logic, taking as initial case study the Contextuality approach of [1]
- 2 studied how path bisimulation behaves on sheaves
- 3 suggested how to capture the notion of sheaf in hybrid path logic



## Conclusions and further work

We have:

- 1 shown that interesting properties of sheaves can be expressed in path logic, taking as initial case study the Contextuality approach of [1]
- 2 studied how path bisimulation behaves on sheaves
- 3 suggested how to capture the notion of sheaf in hybrid path logic

There are quite some open problems, besides those already mentioned:

- completeness, decidability, correspondence for path logic (some work on this already done)?
- how does path logic over topological spaces relate to the topological interpretation of modal logic?
- in light of the analysis of contextuality: is path logic a good logic for context change?

# References



Samson Abramsky and Adam Brandenburger.  
The sheaf-theoretic structure of non-locality and contextuality.  
*New Journal of Physics*, 13(11):113036, 2011.



André Joyal, Mogens Nielsen, and Glynn Winskel.  
Bisimulation from open maps.  
*Information and Computation*, 127(2):164–185, 1996.



Glynn Winskel and Mogens Nielsen.  
Presheaves as transition systems.  
*DIMACS Series in Discrete Mathematics and Theoretical Computer Science*, 29:129–140, 1997.