On Topological Modal Logic of Real Line with Difference Modality

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Plan of Talk

1 Introduction

- Topological semantic for modal logic
- History of the Question

2 Results

- Main results
- Proof sketch

Outline

1 Introduction

• Topological semantic for modal logic

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Topological semantic for modal logic History of the Question

Topological semantic

$$\mathcal{ML}(\Box): \qquad A \rightleftharpoons \bot \mid p_i \mid A \to A \mid \Box A$$

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Topological space $\mathfrak{X} = (X, \mathbf{I})$, where \mathbf{I} is an open operator, $\mathbf{C}Y = -\mathbf{I}(-Y)$ is a closer operator.

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Topological model $(\mathfrak{X}, V), V : PV \to \mathcal{P}(X)$

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$$\begin{array}{lll} V(\bot) &=& \varnothing, & \mathfrak{X}, V, x \not\models \bot, \\ V(A \to B) &=& (X - V(A)) \cup V(B), & \mathfrak{X}, V, x \models A \to B \Leftrightarrow \mathfrak{X}, V, x \models B \lor \mathfrak{X}, V, x \not\models A, \\ V(\Box A) &=& \mathbf{I}V(A), & \mathfrak{X}, V, x \models \Box A \Leftrightarrow \exists U(x) (\forall y \in U(x) \ \mathfrak{X}, V, y \models A). \end{array}$$

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Topological semantic for modal logic History of the Question

Logic of topological space

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 $L_{\Box}(\mathcal{C}) \leftrightarrows \{A \in \mathcal{ML}(\Box) \mid \forall \mathfrak{X} \in \mathcal{C}(\mathfrak{X} \models A)\} \text{ is logic of the class of topological spaces } \mathcal{C} \text{ in language } \mathcal{ML}(\Box). \ L_{\Box}(\mathfrak{X}) \leftrightarrows L_{\Box}(\mathfrak{X})$

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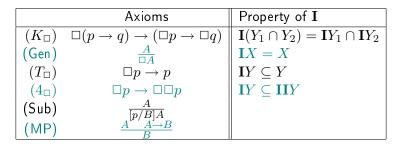
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Logic S4.

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Theorem (McKinsey, Tarski, 1944)

 $L_{\Box}([all \ topological \ spaces]) = \mathbf{S4}$

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Theorem (McKinsey, Tarski, 1944)

 $L_{\Box}([all \ topological \ spaces]) = \mathbf{S4}$

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If \mathfrak{X} is a separable metric dense-in-itself space then $L_{\Box}(\mathfrak{X}) = \mathbf{S4}$.

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Theorem (Ladner, 1977)

S4 is a PSPACE-complete logic.

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Universal modality

$$\begin{split} \mathcal{ML}(\Box, [\forall]) : & \phi \rightleftharpoons \bot \mid p_i \mid \phi \to \psi \mid \Box \phi \mid [\forall] \phi \\ \mathfrak{X}, V, x \models [\forall] A \rightleftharpoons \forall y \in \mathfrak{X}(\mathfrak{X}, V, y \models A) \end{split}$$

Property of connectedness of a topological space is expressible in this language.

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$$\mathcal{ML}\left(\Box,[\neq]\right): \qquad \phi \rightleftharpoons \bot \mid p_i \mid \phi \to \psi \mid \Box \phi \mid [\neq]\phi$$

$$\mathfrak{X}, V, x \models [\neq] A \rightleftharpoons \forall y \in \mathfrak{X} (y \neq x \Rightarrow \mathfrak{X}, V, y \models A)$$

$$[\forall] A \rightleftharpoons [\neq] A \land A$$

The following properties are expressible:

connectedness

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The following properties are expressible:

- connectedness
- density-in-itself

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The following properties are expressible:

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$$[\forall] A \rightleftharpoons [\neq] A \land A$$

The following properties are expressible:

- connectedness
- density-in-itself
- T₀, T₁
- local n-connectedness

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Topological semantic for modal logic History of the Question



Definition

$$\begin{split} &L_{\Box,[\neq]}(\mathcal{C}) \leftrightarrows \{A \in \mathcal{ML}(\Box,[\neq]) \mid \forall \mathfrak{X} \in \mathcal{C}(\mathfrak{X} \models A)\} \text{ -- D-logic of a} \\ &\text{class of topological spaces } \mathcal{C} \text{ in } \mathcal{ML}(\Box,[\neq]). \\ &L_{\Box,[\neq]}(\mathfrak{X}) \leftrightharpoons L_{\Box,[\neq]}(\{\mathfrak{X}\}) \end{split}$$

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Topological semantic for modal logic History of the Question

Known logics

$$\mathbf{S4DEC} \left\{ \begin{array}{c} \mathbf{S4DT_{1}S} \begin{cases} \mathbf{S4} \begin{cases} \mathbf{S4} \begin{cases} (T_{\Box}) \quad \Box p \to p \\ (4_{\Box}) \quad \Box p \to \Box \Box p \\ \\ \mathbf{DL} \end{cases} \begin{cases} (B_{D}) \quad p \to [\neq] \langle \neq \rangle p \\ (\Phi_{D}^{-}) \quad (p \land [\neq]p) \to [\neq] [\neq]p \\ (D_{\Box}) \quad [\forall]p \to \Box p \\ (D_{\Box}) \quad [\forall]p \to \langle p \\ (AT_{1}) \quad [\neq]p \to \langle p \\ (AT_{1}) \quad [\neq]p \land \neg p \land \Box (p \to q) \lor \Box (p \to q) \lor \Box (p \to \neg q) \\ (AC) \quad [\forall] (\Box p \lor \Box \neg p) \to [\forall]p \lor [\forall] \neg p \end{cases} \right.$$

Theorem

 $\begin{array}{l} L_{\Box,[\neq]}([\textit{all topological spaces}]) = \mathbf{S4D} \\ L_{\Box,[\neq]}([\textit{all dense-in-itself spaces}]) = \mathbf{S4D} + (DS) \\ L_{\Box,[\neq]}(\textit{Cantor space}) = \mathbf{S4DT_1S} \qquad L_{\Box,[\neq]}(\mathbb{R}^n) = \mathbf{S4EC}, \ n \geq 2 \end{array}$

all mentioned logics are finitely axiomatizable and decidable.

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$$L_{\Box,[\neq]}(\mathbb{R}) = ?$$

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$$L_{\Box,[\neq]}(\mathbb{R}) = ?$$

$$(AE_2) \qquad [\neq]p \land \neg p \land \Box(p \to \Box Q_1 \lor \Box Q_2 \lor \Box Q_3) \to \\ \to \Box(p \to \neg Q_1) \lor \Box(p \to \neg Q_2) \lor \Box(p \to \neg Q_3),$$

where $Q_1 = q_1 \wedge q_2$, $Q_2 = q_1 \wedge \neg q_2$ and $Q_3 = \neg q_1$.

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$$L_{\Box,[\neq]}(\mathbb{R}) = \mathbf{S4DE_2C} = \mathbf{S4DT_1S} + (AE_2) + (AC)?$$

$$(AE_2) \qquad [\neq]p \land \neg p \land \Box(p \to \Box Q_1 \lor \Box Q_2 \lor \Box Q_3) \to \\ \to \Box(p \to \neg Q_1) \lor \Box(p \to \neg Q_2) \lor \Box(p \to \neg Q_3),$$

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Proof sketch

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Main results

Theorem

 $L_{\Box,[\neq]}(\mathbb{R})$ is not axiomatizable by formulas using predefined finite set of variables; hence it is not finitely axiomatizable.

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Main results

Theorem

 $L_{\Box,[\neq]}(\mathbb{R})$ is not axiomatizable by formulas using predefined finite set of variables; hence it is not finitely axiomatizable.

Decidability of $L_{\Box,[\neq]}(\mathbb{R})$ follows from decidability of monadic second order theory of (\mathbb{R}, \leq) , proved by M.O.Rabin (1969).

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Proof sketch

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The technic is very like the technic in paper of L.Maksimova, D.Skvorcov, V.Shehtman (1979)

Definition

 \mathfrak{X} is a topological space, $F = (W, R, R_D)$ is a finite S4D-frame. Surjective map $f : \mathfrak{X} \to F$ is called *cd-p-morphism*, iff

•
$$\mathbf{C}f^{-1}(w) = f^{-1}(R^{-1}(w)),$$

• $\neg w R_D w \Rightarrow |f^{-1}(w)| = 1.$

Notation $f: \mathfrak{X} \xrightarrow{ca} F$.

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Notation $f: \mathfrak{X} \xrightarrow{cd} F$.

Lemma

$$f: \mathfrak{X} \xrightarrow{cd} \mathcal{F} \Rightarrow \mathbf{L}(\mathfrak{X}) \subseteq \mathbf{L}(\mathcal{F}).$$

Main results Proof sketch

n-equivalent frames

Definition

Formula A is called *n*-formula, if it uses only n first variables. For a set L of formulas $L\lceil n \text{ stands for all } n$ -formulas from L. $F \sim_n F'$ iff $L_{\Box,[\neq]}(F)\lceil n = L_{\Box,[\neq]}(F')\lceil n$.

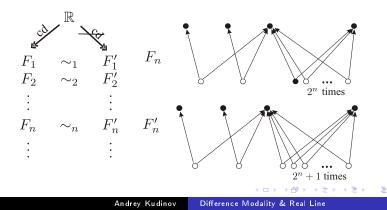
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Main results Proof sketch

n-equivalent frames

Definition

Formula A is called *n*-formula, if it uses only n first variables. For a set L of formulas $L\lceil n$ stands for all n-formulas from L. $F \sim_n F'$ iff $L_{\Box,[\neq]}(F)\lceil n = L_{\Box,[\neq]}(F')\lceil n$.



Main results Proof sketch

Characteristic graph

Theorem

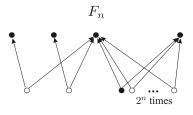
F is a **S4DE**₂**C**-frame, we can construct graph $\Gamma(F)$ such that

$$\mathbb{R} \xrightarrow{cd} F \iff \Gamma(F) - \text{ is an Euler graph.}$$

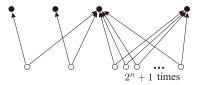
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	Introduction Results Conclusion	Main results Proof sketch	
Characteristic graph			

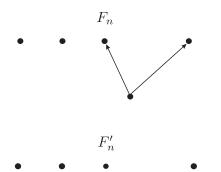






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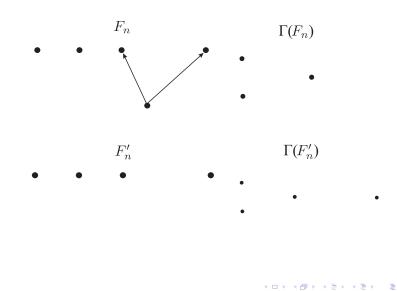


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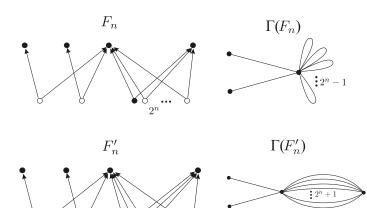
Main results Proof sketch

Characteristic graph



Main results Proof sketch

Characteristic graph



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• $L_{\Box,[\neq]}(\mathbb{R})$ is decidable.

Andrey Kudinov Difference Modality & Real Line

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- L_{□,[≠]}(ℝ) is not axiomatizable by formulas using predefined finite set of variables.

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 - to my supervisor Valentin Shehtman for ideas, advices and supervising.

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