

*Some observations regarding cut-free hypersequent
calculi for intermediate logics*

Frederik Möllerström Lauridsen

UNIVERSITY OF AMSTERDAM (ILLC)

SYSMICS

September 8, 2016

Proof theory for intermediate logics

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Question I:

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Remark

Of course decidability is a necessary requirement, but other than that not much seems to be known.

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A sequent rule (r) is *structural* if its of the form

$$\frac{\Gamma_{11}, \dots, \Gamma_{1n_1} \Rightarrow \Pi_1 \quad \dots \quad \Gamma_{1m}, \dots, \Gamma_{1n_m} \Rightarrow \Pi_m}{\Gamma_{01}, \dots, \Gamma_{0n_0} \Rightarrow \Pi_0} (r)$$

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Examples

$$\frac{\Gamma \Rightarrow \Pi}{\Gamma, \varphi \Rightarrow \Pi} (lw)$$

$$\frac{\Gamma_1 \Rightarrow \Pi_1 \quad \Gamma_2 \Rightarrow \Pi_2}{\Gamma_1 \Rightarrow \Pi_2} (\not{z})$$

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Structural rules give cut-free calculi for a number of substructural logics. Unfortunately, ...

Structural rules

Proposition (Ciabattoni, Galatos & Terui 2008)

Any structural sequent rule is either derivable in LJ or derives every formula in LJ.

Consequently, this approach is *not* helpful when trying to give an (partial) answer to [Question I](#).

Hypersequent rules

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Hypersequents [Mints 1968, Pottinger 1983, Avron 1987]

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Structural hypersequent rules may be defined in the evident way.

Examples

$$\frac{H \mid \Gamma_1, \Gamma_2 \Rightarrow \Pi_1 \quad H \mid \Sigma_1, \Sigma_2 \Rightarrow \Pi_2}{H \mid \Gamma_1, \Sigma_1 \Rightarrow \Pi_1 \mid \Gamma_2, \Sigma_2 \Rightarrow \Pi_2} \quad \frac{H \mid \Gamma_1, \Gamma_2 \Rightarrow}{H \mid \Gamma_1 \Rightarrow \mid \Gamma_2 \Rightarrow}$$

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*Every structural hypersequent rule (r) is equivalent to a (so-called **completed**) structural hypersequent rule (r') such that $\vdash_{\text{HLJ}+(r')} H$ implies $\vdash_{\text{HLJ}+(r')}^{cf} H$, for any hypersequent H .*

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Question III:

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Question III:

For which intermediate logics can we find structural hypersequent calculi? That is, which intermediate logics are determined by hypersequent calculi of the form $\text{HLJ} + \mathcal{R}$, for some set \mathcal{R} of structural hypersequent rules?

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Examples

The logics

$$\text{LC, KC, BTW}_n, \text{BW}_n \ \& \ \text{BC}_n, \quad (n \geq 2)$$

can all be axiomatised by formulas belonging to \mathcal{P}_3 .

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Every \mathcal{P}_3 -formula is equivalent (over HLJ) to a finite set of structural hypersequent rules.

In fact it is not very difficult to show that any intermediate logic admitting a structural hypersequent calculus can be axiomatised by \mathcal{P}_3 -formulas.

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Given an intermediate logic $L := \mathbf{IPC} + \varphi$ with $\varphi \notin \mathcal{P}_3$ there might exist $\psi \in \mathcal{P}_3$ such that $L = \mathbf{IPC} + \psi$. For example:

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$$\begin{aligned} \mathbf{BTW}_n &= \mathbf{IPC} + \bigwedge_{0 \leq i < j \leq n} \left(\neg(\neg p_i \wedge \neg p_j) \rightarrow \bigvee_{i=0}^n (\neg p_i \rightarrow \bigvee_{j \neq i} \neg p_j) \right) \\ &= \mathbf{IPC} + \bigvee_{i=0}^n \left(\bigwedge_{j < i} p_j \rightarrow \neg \neg p_i \right). \end{aligned}$$

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What we need are **semantic criteria** determining whether or not an intermediate logic can be axiomatised by \mathcal{P}_3 -formulas. We provide such criteria, both in terms of the algebraic and the Kripke semantics.

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Definition

We say that an intermediate logic L is $(0, \wedge, 1)$ -stable if whenever $h: \mathfrak{A} \hookrightarrow \mathfrak{B}$ is an $(0, \wedge, 1)$ -embedding of Heyting algebras with $\mathfrak{B} \in \mathbb{V}(L)_{si}$ then $\mathfrak{A} \in \mathbb{V}(L)$.

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Key lemma

An intermediate logic L is $(0, \wedge, 1)$ -stable iff $\mathbb{V}(L)$ is generated by a universal class of Heyting algebras closed under $(0, \wedge, 1)$ -subalgebras.

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For $n \geq 2$ the logic \mathbf{BD}_n does not admit any structural hypersequent calculus,

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For $n \geq 2$ the logic \mathbf{BD}_n does not admit any structural hypersequent calculus, i.e., a calculus of the form $\mathbf{HLJ} + \mathcal{R}$, with \mathcal{R} a set of structural rules.

Semantic characterisation: Kripke frames

Definition

A first-order formula is a *geometric implication* if it is a conjunction of formulas the form

$$\forall \vec{w}(\varphi(\vec{w}) \implies \exists \vec{v}(\psi_1(\vec{w}, \vec{v}) \text{ or } \dots \text{ or } \psi_n(\vec{w}, \vec{v}))),$$

where φ and ψ_k are conjunctions of atomic formulas and the variables \vec{v} do not occur (free) in φ .

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Geometric implications can be used to construct labeled sequent calculi for intermediate and modal logics.

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Definition (Lahav 2013)

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(in the language of partial orders) is said to be *simple* if

1. there is $w_0 \in \vec{w}$ such that every atomic subformula of φ is of the form $w_0 \leq w_l$;
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Examples

$$\forall w_1, \dots, w_{n+1}(\text{AND}_{i=1}^n(w_i \leq w_{i+1}) \implies \text{OR}_{i \neq j}(w_i = w_j)) \quad \wp$$

$$\forall w_0, w_1, w_2((w_0 \leq w_1 \text{ and } w_0 \leq w_1) \implies \exists v (w_1 \leq v \text{ and } w_2 \leq v)).$$

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Let L be an intermediate logic. Then the following are equivalent:

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- 2. L is sound and complete w.r.t. a class of (finite) intuitionistic Kripke frames determined by simple geometric implications.*

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2. Substructural logics: Semantic characterisation of \mathcal{P}_3 -formulas (\mathcal{P}'_3 -formulas) over \mathbf{FL}_{ew} and \mathbf{FL}_e ;
3. Hypersequent calculi for modal logics and stable modal logics.

Thank you for your attention.