

Pseudo-random Graphs and Structures with Good Enough Measures

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Definition

We define the *triangles* in E by:

$$\Delta(E) = \{(x, y, z) \in V^3 \mid (x, y), (y, z), (z, x) \in E\}.$$

Theorem (Triangle Removal Lemma, Szemerédi and Ruzsa)

For every $\epsilon > 0$ there is a $\delta > 0$ such that for any finite V and any graph E on V , if $\mu^3(\Delta(E)) < \delta$ then

There is an $S \subseteq E$ with $\mu^2(S) < \epsilon$ such that $\Delta(E \setminus S) = \emptyset$ (it is possible to remove every triangle by removing a small number of edges).

$$\mu^2(S) = \frac{|S|}{|V|^2} \text{ and } \mu^3(\Delta(E)) = \frac{|\Delta(E)|}{|V|^3}$$

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- $E \subseteq \Gamma \subseteq [V]^2$,
- $\mu^2(\Gamma)$ is very small—say $|\Gamma| \approx \gamma|V|^c$ with $c < 2$, but
- $\mu_\Gamma^2(E) = \frac{|E|}{|\Gamma|} > \epsilon$, and
- Γ is sufficiently pseudorandom.

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- $\mu_\Gamma^2(E) = \frac{|E|}{|\Gamma|} > \epsilon$, and
- There is a set of graphs \mathcal{P} such that $\Gamma \in \mathcal{P}$ and when Γ is chosen randomly,

$$\lim_{|V| \rightarrow \infty} \mathbb{P}(\Gamma \in \mathcal{P}) = 1.$$

Theorem (Kohayakawa, Rödl, Schacht, and Skokan, 2010)

For every $\epsilon > 0$ there is a $\delta > 0$ such that for any finite V , any sufficiently pseudorandom $\Gamma \subseteq [V]^2$, and any $E \subseteq \Gamma$, if $\mu_\Gamma^3(\Delta(E)) < \delta$ then

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Here $\mu_\Gamma^3(\Delta(E)) = \frac{|\Delta(E)|}{|\Delta(\Gamma)|}$. If Γ is chosen randomly so $|\Gamma| \geq C|V|^{3/2}$ then, as $|V| \rightarrow \infty$, the probability that the theorem applies to Γ approaches 1.

Generalizations of triangle removal include:

Theorem (Graph Removal Lemma)

Let H be a fixed finite graph. For every $\epsilon > 0$ there is a $\delta > 0$ such that for any finite V and any graph E on V , if the measure of the set of copies of H (in $\mu^{|H|}$) is $< \delta$ then there is an $S \subseteq E$ with $\mu^2(S) < \epsilon$ such that there are no copies of H in $E \setminus S$.

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Theorem (Hypergraph Removal Lemma)

Let H be any fixed finite k -regular hypergraph. For every $\epsilon > 0$ there is a $\delta > 0$ such that for any finite V and any k -regular hypergraph E on V , if the measure of the set of copies of H (in $\mu^{|H|}$) is $< \delta$ then there is an $S \subseteq E$ with $\mu^k(S) < \epsilon$ such that there are no copies of H in $E \setminus S$.

Theorem (T. 2012, Conlon-Fox-Zhou 2012)

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One approach to theorems like this is to use ultraproducts: suppose that for every n , (V_n, E_n) is a graph with $\mu^2(E_n) \geq \epsilon > 0$ and $|V_n| \rightarrow \infty$.

Then in the ultraproduct $(V, E) = \prod_{\mathcal{U}} (V_n, E_n)$, the measures $\mu^1(S) = \prod_{\mathcal{U}} \frac{|S_n|}{|V_n|}$ and $\mu^2(T) = \prod_{\mathcal{U}} \frac{|T_n|}{|V_n|^2}$ extend to actual σ -additive measures and $\mu^2(E) \geq \epsilon > 0$.

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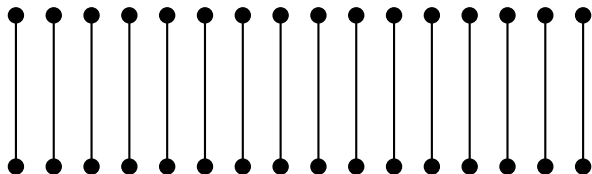
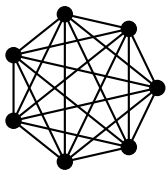
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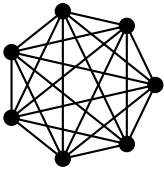
Raw measure theory usually isn't quite enough. For instance, $E \subseteq V^2$ is generally *not* measurable in the product measure. Some additional mechanism (like Keisler's notion of a *graded measure space*) is needed.

When (V_n, Γ_n) are a sequence of graphs with $|\Gamma_n| \approx \gamma |V_n|^c$, $c < 2$, we can always form an ultraproduct (V, Γ) .

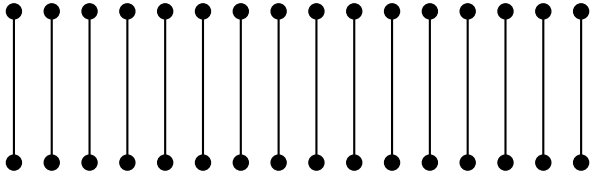
Question

What special properties does the ultraproduct have if the Γ_n were pseudorandom?

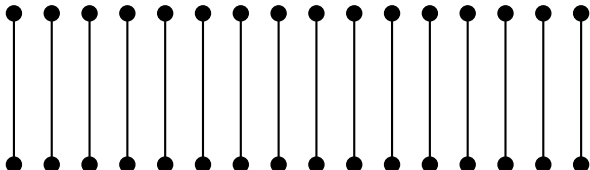
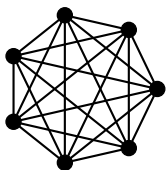




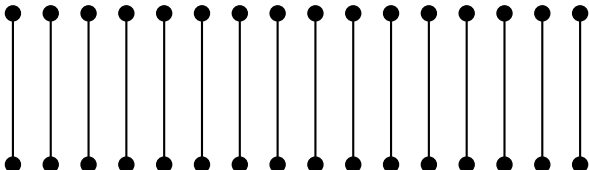
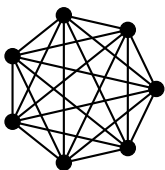
Few vertices,
Many edges



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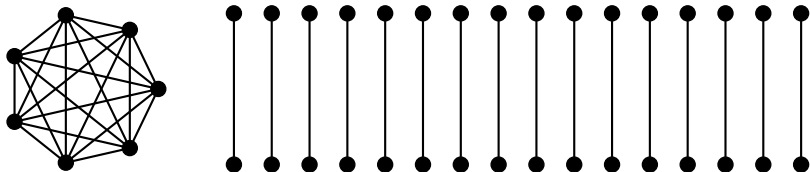


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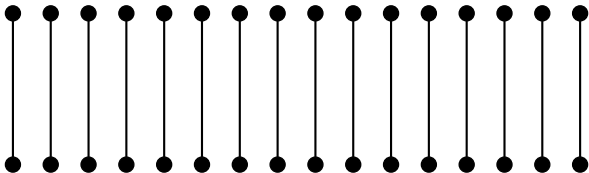
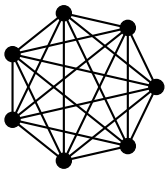
If $g(x, y)$ is a function on pairs of vertices—that is, on edges—then $\int g(x, y)d\mu^2(x, y)$ is the average value over edges present in the graph above.



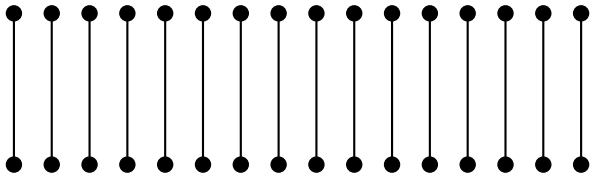
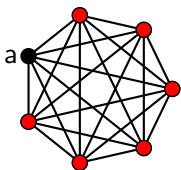
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If $g(x, y)$ is a function on pairs of vertices—that is, on edges—then $\int g(x, y)d\mu_\Gamma^2(x, y)$ is the average value over edges present in the graph above.

Fubini's theorem fails very badly: $\int \chi_\Gamma(x, y)d\mu_\Gamma^2(x, y) = 1$ while $\iint \chi_\Gamma(x, y)d\mu^1(y)d\mu^1(x) \rightarrow 0$.

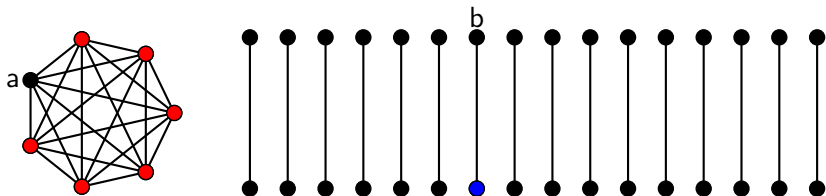


We can define additional measures: for each vertex x , define $\mu_x^1(S) = \frac{|S \cap N_\Gamma(x)|}{|N_\Gamma(x)|}$ where $N_\Gamma(x)$ is the *neighbors* of x in Γ .



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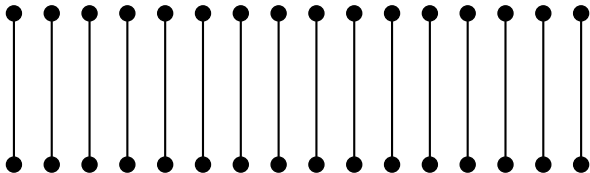
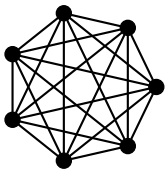
In this case $\mu_a^1(S)$ concentrates on the red vertices.



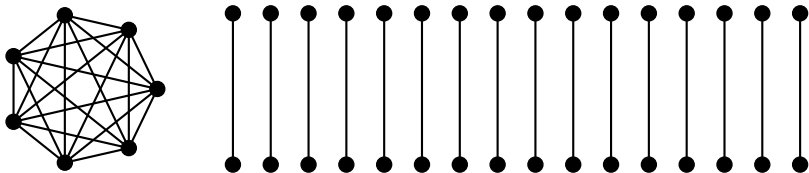
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$\mu_b^1(S)$ is always 0 or 1, depending on whether the blue vertex belongs to S .

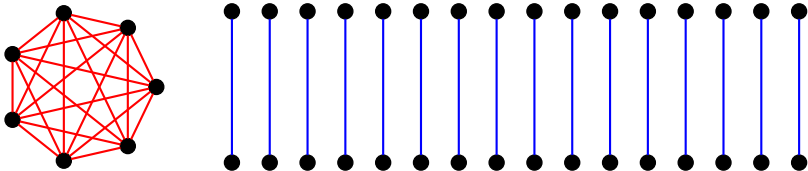


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Let R be the set of red edges. Then:

- $\int \chi_R(x, y) d\mu_{\Gamma}^2(x, y) \rightarrow 1,$
- $\iint \chi_R(x, y) d\mu_x^1(y) d\mu^1(x) \rightarrow 0.$

A natural notion of pseudorandomness is to ask that these integrals should agree:

$$\int g(x, y) d\mu_{\Gamma}^2(x, y) = \iint g(x, y) d\mu_x^1(y) d\mu^1(x).$$

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These two integrals correspond to methods of selecting an edge in Γ : μ_{Γ}^2 selects an edge in one step while $\mu^1 \times \mu_x^1$ first selects a vertex and then extends the vertex to an edge in Γ .

More generally, let (G, E) be any fixed finite (i.e. small) graph. If we want to select a copy of (G, E) in Γ , there are many ways of doing so:

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A useful (but very strong) notion of pseudorandomness is to require that all such methods of counting give the same value. A more reasonable notion is to require this for some fixed finite list of graphs (G, E) .