

Merzlyakov-type theorems after Sela

Part I

Goals & Motivation

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The following chain of groups is elementary

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Theorem (Sela)

The common theory of non abelian free groups T_{fg} is stable.

Questions & Problems

- ▶ *Understand $\text{Def}(T_{fg})$, e.g. definable/interpretable groups, fields;*
- ▶ *Identify regular types;*
- ▶ *Characterize the superstable part;*
- ▶ *Understand forking independence;*
- ▶ *Does T_{fg} has nfcp?*
- ▶ *What does a saturated model of T_{fg} look like?*

\mathbb{F} is a finitely generated non abelian free group.

$\Sigma(\bar{x}, \bar{y}) \subset_{\text{finite}} \langle \bar{x}, \bar{y} \rangle$.

Theorem (Merzlyakov)

Let $\mathbb{F} \models \forall \bar{x} \exists \bar{y} (\Sigma(\bar{x}, \bar{y}) = 1)$. Then there exists a retract $r : G_{\Sigma} \rightarrow \langle \bar{x} \rangle$, where $G_{\Sigma} := \langle \bar{x}, \bar{y} \mid \Sigma(\bar{x}, \bar{y}) \rangle$.

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Theorem (Extended Merzlyakov)

Let $(\bar{b}_n)_{n < \omega}$ be a “test sequence” in \mathbb{F} . Suppose for each n there is \bar{c}_n such that $\mathbb{F} \models \Sigma(\bar{b}_n, \bar{c}_n) = 1$. Then there exists a retract $r : G_{\Sigma} \rightarrow \langle \bar{x} \rangle$.

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Combine “Extended Merzlyakov” with Sela’s “Diophantine envelopes” technique.

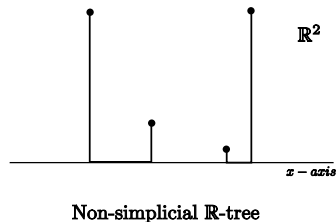
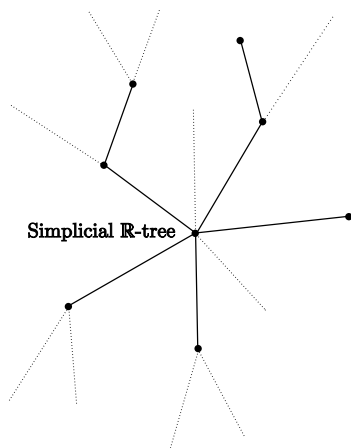
Main tools and notions

- ▶ Real trees (\mathbb{R} -trees), group actions on \mathbb{R} -trees, Rips' Machine;
- ▶ Limit groups, Sela's shortening argument;
- ▶ Towers, Hyperbolic Towers, Diophantine Envelopes.

Real trees

Definition

An \mathbb{R} -tree T is a geodesic metric space such that for any two points $x, y \in T$ there is a unique arc joining them.



$$d((x_1, y_1), (x_2, y_2)) = \begin{cases} |y_2 - y_1| & \text{if } x_1 = x_2 \\ |y_1| + |x_2 - x_1| + |y_2| & \text{if } x_1 \neq x_2 \end{cases}$$

Alternatively: an \mathbb{R} -tree is a geodesic 0-hyperbolic metric space.

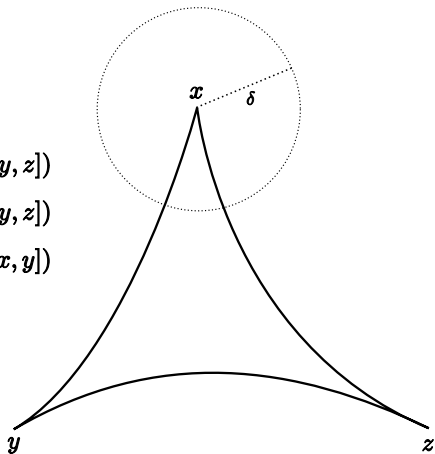
Definition (Rips)

A geodesic metric space is called δ -hyperbolic if every geodesic triangle is δ -thin.

$$[x, z] \subset B_\delta([x, y] \cup [y, z])$$

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Hyperbolic metric spaces

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Definition (Gromov)

A based metric space $(X, *, d)$ is called (δ) -hyperbolic if it satisfies Gromov's three point condition:

- ▶ for $x, y \in X$, let $(x \cdot y)_* = \frac{1}{2}(d(*, x) + d(*, y) - d(x, y))$;
- ▶ then for any $x, y, z \in X$, $(x \cdot y)_* \geq \min((x \cdot z)_*, (y \cdot z)_*) - \delta$.

Group actions on \mathbb{R} -trees

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Motivation: Bass-Serre Theory

Theorem

Suppose G acts freely on a simplicial tree T (a contractible $1 \geq$ -dimensional CW-complex). Then G is a free group.

Proof.

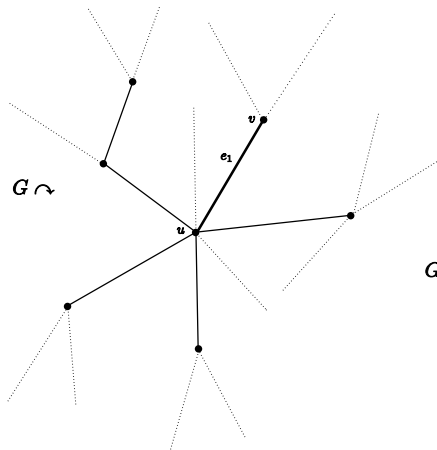
G acts freely $\Rightarrow G$ acts by a covering space action. Thus, $G \cong \pi_1(T/G)$, but T/G is a graph. □

Corollary (Nielsen-Schreier Theorem)

Let $G < \mathbb{F}$. Then G is a free group.

Theorem (Main Theorem)

Suppose G acts (without inversions) on a simplicial tree T . Then G splits as a graph of groups, where the underlying graph is T/G , vertex groups come from vertex stabilizers and edge groups from edge stabilizers.



$$\begin{array}{c} \text{-----} \text{Stab}_G(e_1) \text{-----} \\ \text{Stab}_G(u) \qquad \qquad \qquad \text{Stab}_G(v) \end{array}$$

$$G \cong \text{Stab}_G(u) *_{\text{Stab}_G(e_1)} \text{Stab}_G(v)$$

Some types of actions on \mathbb{R} -trees

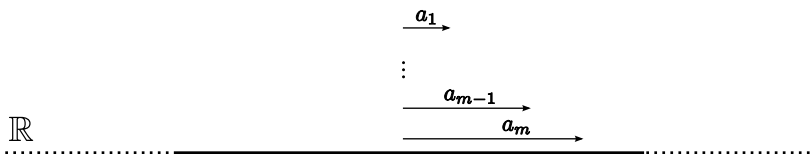
Suppose G acts on a real tree T (by isometries). Then the action is of:

- ▶ *Discrete type*, if branching points in T form a discrete closed set and the orbit of each point is discrete. It is essentially an action on a simplicial tree as in the Bass-Serre theory;
- ▶ *Axial type*, if T is isometric to \mathbb{R} , and the orbit of each point is dense in T ;
- ▶ *Surface type*, if $\ker \lambda \hookrightarrow G \twoheadrightarrow L$ where $\ker \lambda$ is the kernel of the action and $L := \pi_1(\Sigma)$, where Σ is a surface with (possibly empty) boundary carrying an arational measured foliation and T is dual to $\tilde{\Sigma}$, i.e. T is the lifted leaf space in $\tilde{\Sigma}$ after identifying leaves of distance 0 (with respect to the pseudometric induced by the measure);

Axial type

- ▶ Let $a \in \mathbb{R}$ and $f_a \in Isom^+(\mathbb{R})$ be defined by $f_a(x) = a + x$;
- ▶ Let $\mathbb{Z}^m := \langle z_1, \dots, z_m \rangle$ and $h : \mathbb{Z}^m \rightarrow Isom^+(\mathbb{R})$ defined as follows:

$$h(z_i) = f_{a_i} \text{ and } \{a_1, \dots, a_m\} \text{ is linearly independent}$$



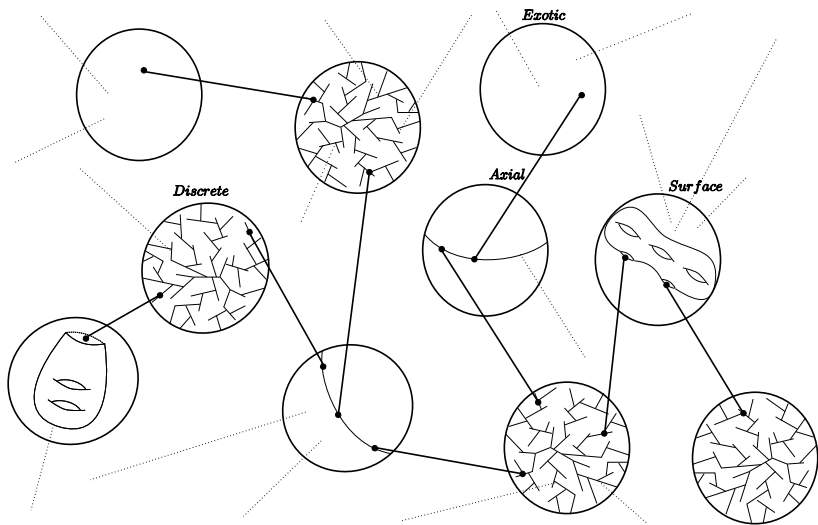
Rips' Machine

Suppose G acts on a real tree T . Then the action is:

- ▶ *minimal*, if there is no G -invariant proper subtree;
- ▶ *non-trivial*, if there is no globally fixed point;
- ▶ *super-stable*, if for any arc I and subarc $J \subset I$ we have that $Stab(J) \neq Stab(I) \Rightarrow Stab(I) = \{1\}$.

Theorem (Rips' Machine)

Let G be a finitely generated group. Suppose G acts non-trivially and minimally on an \mathbb{R} -tree T . Moreover, assume that the action is super-stable and tripod stabilizers are trivial. Then the action can be understood in terms of simpler components which are of discrete, axial, surface or exotic type



Bestvina-Paulin Method

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Let G be a (discrete) group and consider the space of G -equivariant pseudo-metrics equipped with the compact-open topology.

Recall that:

$$(d_i)_{i < \omega} \rightarrow d \text{ if and only if } d_i(1, g) \rightarrow d(1, g) \forall g \in G$$

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- ▶ An action $G \curvearrowright (X, *, d_X)$ on a based metric space induces a G -equivariant pseudo-metric:

$$d(g, h) = d_X(g \cdot *, h \cdot *)$$

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- ▶ A morphism $h : G \rightarrow H$ (H finitely generated) induces an action $G \curvearrowright X_H$:

$$(g, x) \mapsto h(g)x$$

Theorem A

Let Γ be a δ -hyperbolic group. Let $(h_n)_{n < \omega} : G \rightarrow \Gamma$ be a sequence of pairwise non-conjugate morphisms. Then there exists a sequence of base points $(*_n)_{n < \omega}$ in X_Γ and a sequence of rescaling constants $(r_n)_{n < \omega} \in \mathbb{R}^+$ such that a subsequence of the induced pseudo-metrics $(d_n/r_n)_{n < \omega}$ converges to a pseudo-metric d which is induced by a non-trivial action of G on a real tree $(T, *)$.

Proof.

Fix a finite generating set S for G . Consider the function $f_n : X_\Gamma \rightarrow [0, \infty)$, given by:

$$f_n(x) = \max_{s \in S} \{d_{X_\Gamma}(x, h_n(s) \cdot x)\}$$

- ▶ Take $*_n$ to be a point minimizing the value of f_n ; and
- ▶ $r_n = f_n(*_n)$.



- ▶ $f_n(x) = \max_{s \in S} \{d_{X_\Gamma}(x, h_n(s) \cdot x)\}$;
- ▶ let $*_n$ be a point minimizing the value of f_n and $r_n = f_n(*_n)$;
- ▶ $r_n \rightarrow \infty$ (Hint: h_n are pairwise non-conjugate);
 - ▶ Suppose not, and $r_n < M$;
 - ▶ then for each h_n there is $\gamma_n \in \Gamma$ such that $|\gamma_n^{-1} h_n(s) \gamma_n|_\Gamma < M$ (assume that $*_n$ is a vertex in X_Γ and take $\gamma_n = *_n$);
 - ▶ so $d_{X_\Gamma}(\gamma_n, h_n(s) \cdot \gamma_n) \leq \max_{s \in S} \{d_{X_\Gamma}(\gamma_n, h_n(s) \cdot \gamma_n)\} < M$;
 - ▶ but only finitely many morphisms exist that send the generating set of G in the ball of radius M , a contradiction.
- ▶ let $\hat{d}_n := \frac{d_n}{r_n}$. Then $\hat{d}_n(1, s) \leq 1, \forall s \in S$;
 - ▶ $d_n(1, s) = d_{X_\Gamma}(*_n, h_n(s) \cdot *_n)$; and
 - ▶ $r_n = \max_{s \in S} \{d_{X_\Gamma}(*_n, h_n(s) \cdot *_n)\}$.
- ▶ a subsequence of $(\hat{d}_n)_{n < \omega}$ converges to d (Exercise);
- ▶ $(G, 1, \hat{d}_n)$ is $\frac{\delta}{r_n}$ -hyperbolic, thus $(G, 1, d)$ is 0-hyperbolic.

Lemma (Connecting the dots)

Let $(X, *, d)$ be a 0-hyperbolic metric space. Then there exists an \mathbb{R} -tree (T, d_T) and an isometric embedding $i : X \rightarrow T$ such that:

- ▶ no proper subtree of T contains $i(X)$;
- ▶ furthermore, if a group G acts by isometries on X , then the action extends to an isometric action on T .

- ▶ $f_n(x) = \max_{s \in S} \{d_{X_T}(x, h_n(s) \cdot x)\}$;
- ▶ let $*_n$ be a point minimizing the value of f_n and $r_n = f_n(*_n)$;
- ▶ $r_n \rightarrow \infty$ (Hint: h_n are pairwise non-conjugate);
- ▶ let $\hat{d}_n := \frac{d_n}{r_n}$. Then $\hat{d}_n(1, s) \leq 1, \forall s \in S$;
- ▶ a subsequence of $(\hat{d}_n)_{n < \omega}$ converges to d ;
- ▶ $(G, 1, \hat{d}_n)$ is $\frac{\delta}{r_n}$ -hyperbolic, thus $(G, 1, d)$ is 0-hyperbolic;
- ▶ d is induced by an action of G on the real tree $(T, *, d_T)$;
 - ▶ $d(1, g) = d_T(*, g \cdot *)$, for any $g \in G$.

Lemma (Approximating Sequences)

Assume $(X_\Gamma, *_n, d_{X_\Gamma})_{n < \omega}$ “converges” to $(T, *, d_T)$ as in Theorem A. Then for any $x \in T$, the following hold:

- ▶ there exists a sequence $(x_n)_{n < \omega} \in X_\Gamma$ such that $\frac{d_{X_\Gamma}}{r_n}(x_n, g \cdot *_n) \rightarrow d_T(x, g \cdot *)$ for any $g \in G$, we call such a sequence an approximating sequence;
- ▶ if $(x_n)_{n < \omega}$ is an approximating sequence for x , then $(g \cdot x_n)_{n < \omega}$ is an approximating sequence for $g \cdot x$;
- ▶ if $(x_n)_{n < \omega}, (y_n)_{n < \omega}$ are approximating sequences for x, y respectively, then $\frac{d_{X_\Gamma}}{r_n}(x_n, y_n) \rightarrow d_T(x, y)$.

- ▶ $f_n(x) = \max_{s \in S} \{d_{X_\Gamma}(x, h_n(s) \cdot x)\}$;
- ▶ let $*_n$ be a point minimizing the value of f_n and $r_n = f_n(*_n)$;
- ▶ $r_n \rightarrow \infty$ (Hint: h_n are pairwise non-conjugate);
- ▶ let $\hat{d}_n := \frac{d_n}{r_n}$. Then $\hat{d}_n(1, s) \leq 1, \forall s \in S$;
- ▶ a subsequence of $(\hat{d}_n)_{n < \omega}$ converges to d ;
- ▶ $(G, 1, \hat{d}_n)$ is $\frac{\delta}{r_n}$ -hyperbolic, thus $(G, 1, d)$ is 0-hyperbolic;
- ▶ d is induced by an action of G on the real tree $(T, *, d_T)$;
- ▶ let $x \in T$ be a globally fixed point and $(x_n)_{n < \omega}$ be an approximating sequence for x . Then $\frac{d_{X_\Gamma}}{r_n}(x_n, s \cdot x_n) \rightarrow 0$ for any $s \in S$, a contradiction to the choice of $*_n$.

Theorem A

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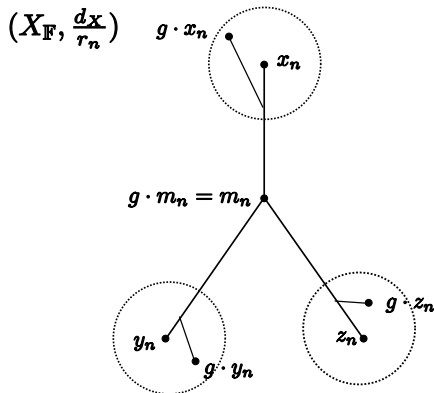
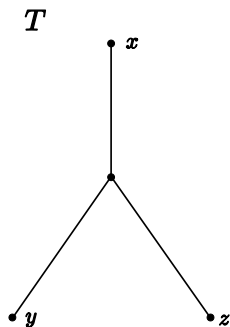
Theorem B

Assume the hypothesis of Theorem A and moreover that Γ is torsion-free. Let $G \curvearrowright^\lambda T$ be the action in the limit. Then $G/\ker \lambda$ acts on T as follows:

- ▶ tripod stabilizers are trivial;
- ▶ arc stabilizers are abelian;
- ▶ the action is super-stable.

Proof of Theorem B (case $\Gamma := \mathbb{F}$)

Suppose g fixes a tripod in T . Then $h_n(g)$ fixes m_n for all large enough n , but then $h_n(g) = 1$ for all large enough n . Thus $g \in \ker \lambda$.



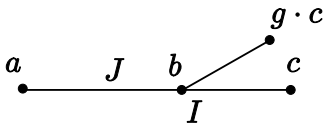
Claim I: Arc stabilizers are abelian.

Proof: Exercise.

Claim II: The action is super-stable.

Proof:

- ▶ Let J be a subarc of I , with $Stab(J) \neq Stab(I)$ and $Stab(I) \neq \{1\}$;
- ▶ Suppose $g \in Stab(J) \setminus Stab(I)$;



- ▶ Let $\gamma \in Stab(I)$;
- ▶ Since γ commutes with g (Claim I), we have that γ fixes a tripod, thus γ is trivial, a contradiction.

Definition

The quotient $G/\ker\lambda$ obtained by a sequence $(h_n)_{n<\omega} : G \rightarrow \mathbb{F}$ is called a limit group.

Theorem (Sela)

Let L be a limit group. Then:

- ▶ *L is finitely presented;*
- ▶ *every abelian subgroup is finitely generated;*
- ▶ *either L is abelian or it admits a non-trivial cyclic splitting.*

Fact

Let L be a finitely generated group. The following are equivalent:

- ▶ *L is a limit group;*
- ▶ *L is ω -residually free;*
- ▶ *$L \models Th_{\forall}(\mathbb{F})$ for some free group \mathbb{F} (including \mathbb{Z});*